

# 产品规格书

# PRODUCT SPECIFICATION

客户名称Buyer Name	
客户料号Buyer Part No.	
客户承认签章 Buyers Approval & Signatures	

文件编号Spec No.		版本	A/1
品名描述 Product Description	圆柱直流马达 Cylindrical DC motor		
型号Part No.	VZ30C1B839981		
送样日期Date			
设计Designed by	审核Checked by	批准App	proved by
野梦和	F4S \$	vs.	W. R
2020.07.01	2020.07.01	2020	.07.01

www.vybronics.com sales@vybronics.com



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# **Records of Revision**

Rev. No.	Rev. Date	Page No.	Revised Item	Reason
A/0	2017.5.25	/	产品颁布/ Release for Production	
A/1	2020.07.01	/	changed company name from JINLONG MACHINERY to VYBRONICS, changed part # from Z30C1B839981 to VZ30C1B839981	Rebranding



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# Preface:

Thank you very much for your selecting the Vybronics VZ30C1B839981 vibrator. Our products have stable performance. To obtain maximum performance from the product, please read this specification first, and keep it handy for future reference.



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#### 1. SCOPE

This document contains specific electrical and mechanical characters, critical characteristics, reliability tests, packaging condition, quality assurance, reflow profile and etc..

#### 2. MECHANICAL CHARACTERISTIC

2.1. Mechanical drawing

2.2. Axial play of shaft

2.3. Counter weight density:

See appendix 2

0.3 mm Max

17.0 g / cc Min

2.4. Mechanical noise of motor operating at rated speed: 45 dB Max A-weighting Background noise 26dB.(Measured distance 10 cm, see appendix 1 Figure 1.1).

#### 3. ELECTRICAL CHARACTERISTICS

3.1. Vibrator positioning: Horizontal
3.2. Operating voltage: 3.0 V
3.3. Operating voltage range: 2.3– 3.6V
3.4. Load current at operating voltage: 85 mA Max
3.5. Starting current at operating voltage: 100 mA Max

3.6. Insulation resistance and voltage break down: at 100V DC, 1MΩ Min and above

3.7. Terminal resistance: $30.0\pm5.0\Omega$ 3.8. Load speed: $12000\pm2500 \text{ rpm}$ 3.9. Rotation direction:C.W. & C.C.W3.10. Motor vibration Force:0.20 G Min

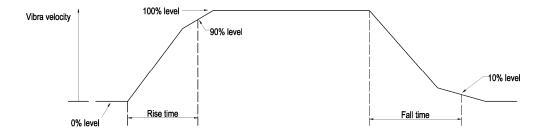
(The G-force is 0.20G min when the motor is under the loading of 100g at rated voltage,  $\,$ 

see appendix 1 Figure 1.2)

3.11. Rise time (see picture 1) 100 ms Max 3.12. Rree Fall time (see picture 1) 70 ms Max

-From zero to 90% of nominal speed

-From nominal velocity to 10% of nominal speed



Picture 1 RPM rise and fall time

3.13 Standard loaded starting voltage: Under standard loaded condition, towards C.W. rotor shall



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move in all position at 2.3V (counterweight should be turned slowly at 360°)

All mechanical and electrical measurements should measured at room temperature and ordinary humidity.

#### 4. ADDITIONAL INFORMATION

4.1. Vibrator weight

0.75g 30N Min

- 4.2. Pull out strength of counter weight and shaft 30N
- 4.3. Acceleration level at nominal RPM (Grms) (test jig mounted in freely suspended)
- 4.4. Speed and current variation (function of temperature, -20°C to +70°C)

#### 5. CRITICAL CHARACTERISTICS

- 5.1. Functional dimensions
- 5.2. Rated current at specified rotating speed
- 5.3. Operating speed at operating voltage
- 5.4. Starting current at operating voltage
- 5.5. Min. starting Voltage

#### 6. ENVIRONMENTAL CHARACTERISTICS

6.1. Operating temperature ranges: -20°C to +70°C 6.2. Storage temperature ranges: -40°C to +85°C

### 7. RELIABILITY TESTS

7.1 We have already performed reliability tests and measure nom rotation speed, nom load current, nom resistance, nom starting currents and nom starting voltage before and after tests, please check following table1 for detail reliability test information. Each test we use at least 10 samples for verification.

	Items	Test conditions	Judgment
7.2	Low	Storage test	No mechanical damage.
	temperature	-40±3°C/96h, recovery 1~2h	Normal performance of
	storage test	Measurements with test jig.	vibrator.
			(Max +/-30% variation of
			nom RPM)

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7.3	High temperature storage test	Storage test 80±3°C/96h, recovery 1~2h Measurements with test jig.	No mechanical damage.  Normal performance of vibrator.  (Max +/-30% variation of nom RPM)
7.4	Temperature cyclic test	Storage test Temperature & humidity: +80±3°C/6h(RH85%); -40±3°C/6h with 6h maximum transition time between temperatures. 24h/cycles, totally 6 cycles. Recovery 1~2h. Performance check daily. Measurements with test jig.  (1 cycle)  80±3°C  85%RH  25±5°C  50%RH  -40±3°C  3H 6H 6H 6H 3H 1~2H time	No mechanical damage. Reduced performance of vibrator. (Max +/-30% variation of nom RPM)
7.5	Thermal shock test	Storage test Temperature & humidity: -40±3°C/30minutes; +85±3°C/30minutes with a 20sec maximum transition time between temperatures. 1h/cycle, totally 50 cycles. Recovery 1~2h. Measurements with test jig.  (1 cycle) 85±3°C  -40±3°C  30minutes 20sec 30min. 20sec time	No mechanical damage. Normal performance of vibrator. (Max +/-30% variation of nom RPM)
7.6	Room temperature lifetime test	Operational test: apply operating voltage Temperature & humidity: 25±3℃, RH 50% On/off time: 2.5s on/off, 300,000 cycles. Performance check: before, after test and every 20,000 cycles. Recovery 1-2h. Measurements with test jig.	No mechanical damage.  After 100,000cycles:  Normal performance of vibrator. (Max +/-30% variation of nom RPM)  After 300,000cycles: The vibrator should operate.



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7.7 High temperature lifetime test		Operational test: apply	operating voltage	No mechanical damage.
		Temperature : 55±3°C		Normal performance of
		On/off time: 2.5s on/off	, 53,000 cycles.	vibrator.
		Performance check: be	efore, after test and eve	ry (Max +/-30% variation of
		20,000 cycles.		nom RPM)
		Recovery 1~2h. Meas	surements with test jig.	
7.8 Low		Operational test: apply	operating voltage	No mechanical damage.
	temperature	Temperature : -20±3°C		Normal performance of
	lifetime test	On/off time:2.5s on/off,	53,000 cycles.	vibrator.
		Performance check: be	efore, after test and eve	ry (Max +/-30% variation of
		20,000 cycles.		nom RPM)
		Recovery 1~2h. Meas	urements with test jig.	
7.9	H₂S corrosion	Storage test		No mechanical damage.
	test	Concentration: 3±1ppm		Normal performance of
		Temperature & humidity: 40±3°C, RH 80%		vibrator.
		Exposure time: 24hour	S	(Max +/-30% variation of
				nom RPM)
7.10	Free Fall	Mount the vibrator in th	e dummy box.(dummy	box No mechanical damage.
		weight 100g), Drop height 1.5 m onto concrete. 3 times in each 6 directions.		e. 3 Normal performance of
				vibrator.
		Measurements with test jig.		(Max +/-30% variation of
				nom RPM)
7.11	Random	3axes, 10minutes per a	xis, 6.06Grms	No mechanical damage.
	vibration test	Frequency (Hz)	A.S.D.(G <sup>2</sup> /Hz)	Normal performance of
		20	0.0098	vibrator.
		80	0.04	(Max +/-30% variation of
		350	0.04	nom RPM)
		2000	0.0069	
		Measurements with tes	st jig.	
7.12	Shock test	Shock test Time of test and direction: 3times in each 6 direction. Total 18 times.		No mechanical damage.
				Normal performance of
		Acceleration: Half-sinu	soidal 500G	vibrator.
		Duration:2ms		(Max +/-30% variation of
				nom RPM)

Table1 Reliability test

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#### 8. EXPECTED SHIPPING AND STORAGE CONDITIONS

8.1. Relative humidity

8.2. Temperature

-5°C~40°C

8.3. Sulphur dioxide average

0.3 mg/m³

8.4. Sulphuretted hydrogen average

0.1 mg/ m³

8.5. Storage period

12 months

(Vibrator has to be rotated at least once within 12 months from the date of receipt)

#### 9. QUALITY ASSURANCE

All critical parameters are 100% in control. The symbols "◆" apply to all parameters identified as critical parameters in all process. And before mass production approval, we use Process Capability Study (PCS) to conduct all critical parameters in mass production. Based on PCS the final quality controls will be agreed. Quality assurance for mass production:

- Lot acceptance rate (LAR)
- First pass yield (FPY)
- Outgoing quality level

Each final packing containing Out-going inspection data sheet (n=35pcs)

Inspection item: Load speed

Load current Starting current Starting voltage Coil resistance

- Customer reject material rate
- Customer satisfaction
- Cpk/Cp control for all critical parameters (except starting voltage)

#### 10. MATERIALS

- Counterweight
- Brush
- Commutator
- Case
- Terminal
- Bracket
- Washer
- End cover
- Bearing
- Magnet
- Copper wire
- Shaft
- Core
- Varistor

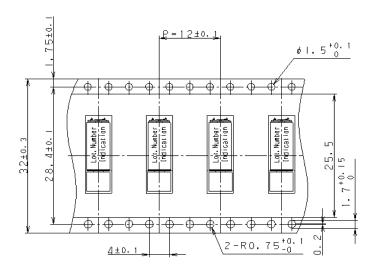
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P.S.: All the materials included in vibrator can meet 2002/95/EC & Vybronics RoHS requirement

#### 11. PACKAGING CONDITION

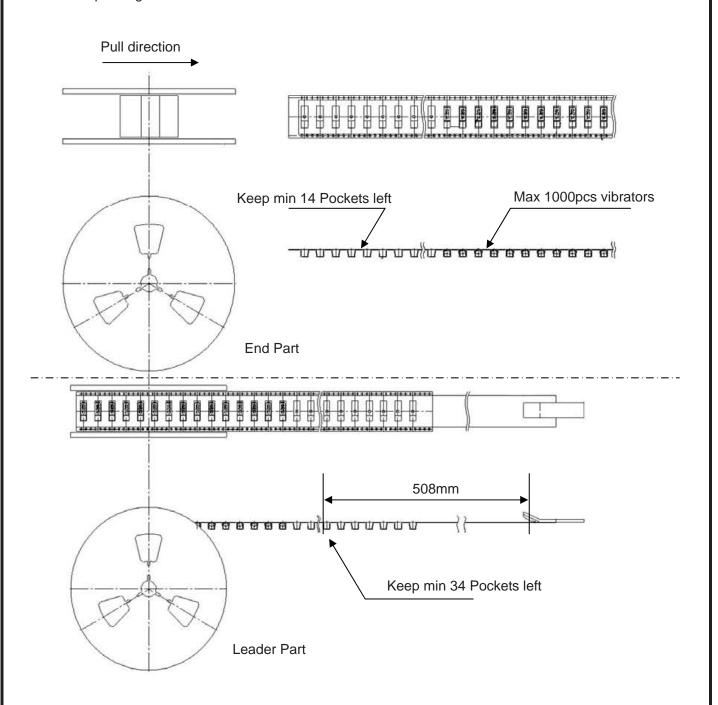
A detailed mechanical drawing for packing condition as followed with dimensions and tolerances: 12.1 Smallest packing



Picture 3 Smallest packing condition

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## 11.2 Reel packing condition

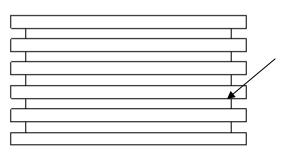


Picture 4 Reel packing condition

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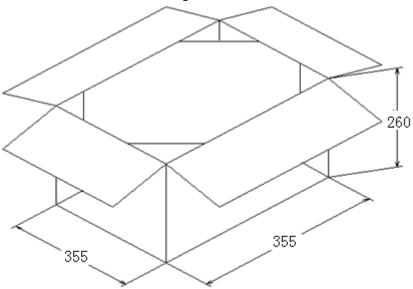
## 11.3 Final packing condition

## 1000pcs/reel X 6reel= total 6000pcs



During the vibrator handle or shipping, counterweight must be faced to upper side.

## Double wall corrugated cardboard



Picture 5 Final packing condition

## 11.4 Accessories included in final package

Out-going inspection data sheet (n=35pcs) will be attached for each lot, we do implemented inspection after reflow. Inspection item including:

Load speed

Load current

Starting current

Starting voltage

Coil resistance

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#### 12. RECOMMENDED REFLOW PROFILE FOR VIBRATOR

#### 12.1 Definitions

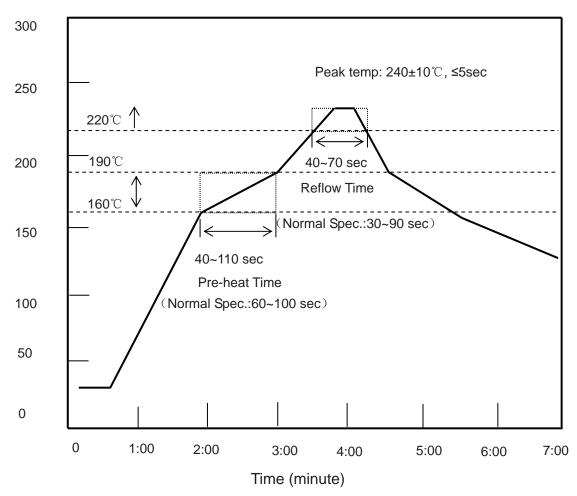
Reflow Profile = Time vs. temperature plot
Peak temperature = Maximum temperature reached on the component
Convection = Forced air heating

### 12.2 Recommended temperature check method of reflow furnace

The reflow furnace used should be 100% convection reflow. Thermocouples should be securely attached to the top surface of vibrator to insure the temperature exposure is met. Profile should be recorded by data acquisition for future reference.

#### 12.3 Recommended reflow Profile for Pb-Free soldering

# Temperature(°C)



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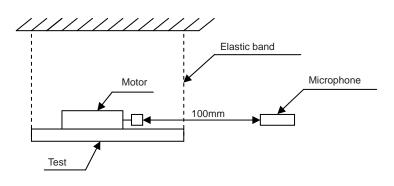
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#### 13. NOTES ON USE

- 13.1 Pay attention to the voltage and current ranges which applied to the vibrator, and use the vibrator in accordance with this specification, otherwise, it will reduce the life and performance of the vibrator.
- 13.2 Do not use hot gun to puff the surface of vibrator from PCB directly.
- 13.3 Do not locking the motor with current applied for long time, which may cause the motor to overheat and short circuit.
- 13.4 Do not exert pressure the terminals, otherwise, it will result in terminal deformation.
- 13.5 Do not bring magnetized objects near or contact with the surface of vibrator, which will demagnetize the magnetism of vibrator and result in noise failure.

## Appendix 1

Figure 1.1: Mechanical noise measurements setup



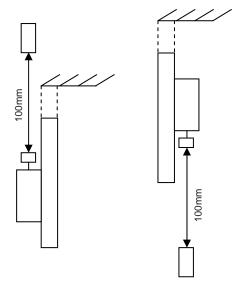


Figure 1.2: Test jig, weight 100g

